

FOURIER SLICE THEOREM

1D F.T. OF $g(p, \theta)$:

$$G(\omega, \theta) = \int g(p, \theta) e^{-2\pi i \omega p} dp$$

↑ FREQUENCIES
IN $g(p, \theta)$
↑ FIXED

$$G(\omega, \theta) = \int \int \int f(x, y) \delta(x \cos \theta + y \sin \theta - p) dx dy e^{-2\pi i \omega p} dp$$

$$= \int \int f(x, y) \left[\int \delta(x \cos \theta + y \sin \theta - p) e^{-2\pi i \omega p} dp \right] dx dy$$

$$= \int \int f(x, y) e^{-2\pi i \omega (x \cos \theta + y \sin \theta)} dx dy$$

$$= \left[\int \int f(x, y) e^{-2\pi i (xu + yv)} dx dy \right] \begin{matrix} u = \omega \cos \theta \\ v = \omega \sin \theta \end{matrix}$$

$$= \left[F(u, v) \right] \begin{matrix} u = \omega \cos \theta \\ v = \omega \sin \theta \end{matrix}$$

SO THE 1D F.T. OF $g(\rho, \theta)$ IS THE
 SAME AS THE 2D F.T. OF $F(x, y)$
 EVALUATED AT $(W \cos \theta, W \sin \theta)$

$$G(W, \theta) = \left[F(u, v) \right]_{\substack{u = W \cos \theta \\ v = W \sin \theta}} \\ = F(W \cos \theta, W \sin \theta)$$

FOR FIXED θ , $F(W \cos \theta, W \sin \theta)$

IS A LINE IN F IN DIRECTION $(\cos \theta, \sin \theta)$

PASSING THROUGH $F(0, 0)$

[FIG 5.41]

FILTERED BACKPROJECTION

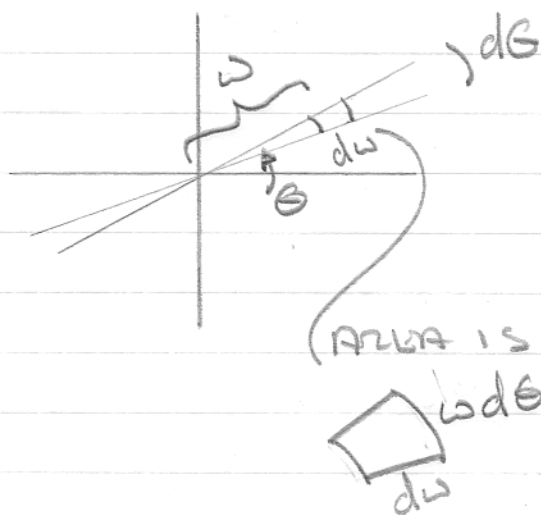
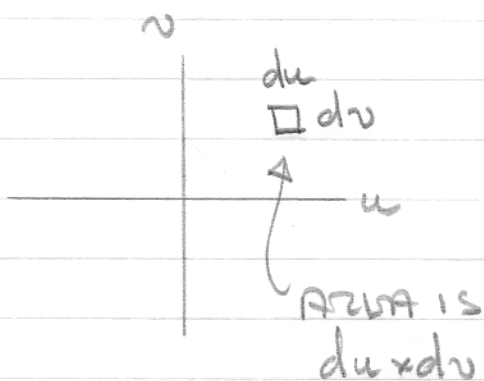
PLAIN BACKPROJECTION DIDN'T WORK WELL
(DUE TO HALOS)

[FIG 5.39, 5.40]

IDFT: USE INVERSE F.T. TO RECONSTRUCT
 $f(x,y)$

$$F(x,y) = \int \int_{v,u} F(u,v) e^{2\pi i(ux+vy)} du dv$$

REPARAMETERIZE THE u,v PLANE OF F
TO USE θ AND w



$$\int \int_{v,u} \dots du dv$$

$$\int \int_{\theta,w} \dots |w| dw d\theta$$

↑ INCREASE
w < 0

AND $(u,v) = (w \cos \theta, w \sin \theta)$

$$F(x, y) = \int_{\theta} \int_{\omega} F(\omega \cos \theta, \omega \sin \theta) e^{2\pi i \omega (x \cos \theta + y \sin \theta)} |\omega| d\omega d\theta$$

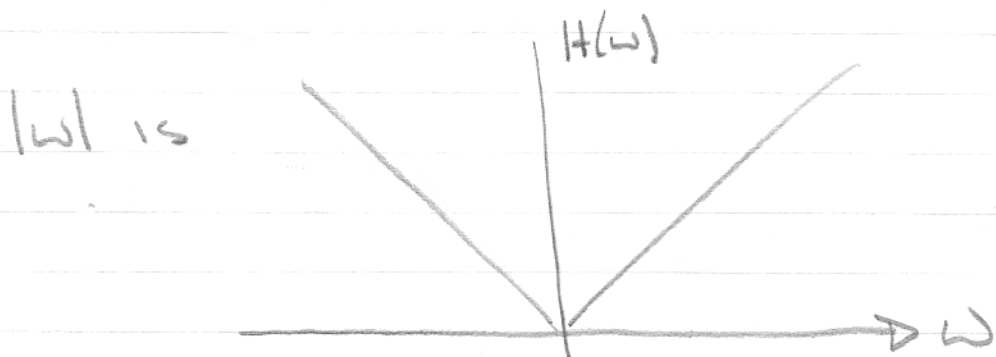
Fourier slice theorem

$$= \int_{\theta} \int_{\omega} G(\omega, \theta) e^{2\pi i \omega (x \cos \theta + y \sin \theta)} |\omega| d\omega d\theta$$

$$= \int_{\theta=0}^{\pi} \left[\int_{\omega} |G(\omega, \theta)| e^{2\pi i \omega p} d\omega \right] d\theta$$

$p = x \cos \theta + y \sin \theta$

THIS IS G MULTIPLIED BY A FILTER, $H(\omega) = |\omega|$



WE COULD INSTEAD CONVOLVE THE
INVERSE F.T. OF H WITH THE INVERSE
F.T. OF G :

$$\int_{\omega} H(\omega) G(\omega, \theta) e^{2\pi i \omega p} d\omega$$

$p = x \cos \theta + y \sin \theta$

$$= h(p) * g(p, \theta)$$

$p = x \cos \theta + y \sin \theta$

$$\text{So } f(x, y) = \int_{\theta=0}^{\pi} h(p) * g(p, \theta) d\theta$$

$$p = x \cos \theta + y \sin \theta$$



FILTERED

BACKPROJECTION

STEPS TO RECONSTRUCT $f(x, y)$

FOR EACH θ_k IN $[0, \pi)$:

- USE CT TO FIND $g(p, \theta_k)$

- COMPUTE $h(p) * g(p, \theta_k) = (h * g)_k(p)$

FOR EACH (x, y) :

$$- f(x, y) = \sum_{\theta_k} (h * g)_k(x \cos \theta_k + y \sin \theta_k)$$



EQUIVALENT TO 'SMEARING'
EACH $(h * g)_k$ ACROSS
THE WHOLE IMAGE

FILTER $H(\omega)$

$$H(\omega) = |\omega|$$

"RAMP-LIKE FILTER"

(RAMPACHANDRAN AND
LAKSHMINARAYANAN)



SHARP DROPOFF AT EDGES
RESULTS IN RINGING

$$H(\omega) = c + (c-1) \cos \frac{2\pi\omega}{R}$$

"HANNING FILTER"

OTHER FILTERS EXIST

[FIG 5.42]

[SEE APPLET

BIGLOW.EPFL.CH/DEMO/STOMOGRAPHY/DEMO.HTML]

FAS-IBAM CT

{ FIG 5.45 }

- DERIVATION IS MORE COMPLICATED
- COULD CONVERT TO A PARALLEL-IBAM PROBLEM, BUT SAMPLING IS NOT REGULAR.

CONV-IBAM CT

- EVEN WORSE DERIVATION
- APPROXIMATIONS USED, BUT RECONSTRUCTED IS GOOD

SPIRAL CT

- NEVER HAVE $g(p, \theta)$ IN SAME Z PLANE
- MUST INTERPOLATE IN Z